



# Algorithm Analysis and Data Structures

## CSCI 7432 – Fall 2022

### DFS-Based Algorithms

**Dr. Yao XU**

Assistant Professor

Department of Computer Science

Georgia Southern University

**Email:** [yxu@georgiasouthern.edu](mailto:yxu@georgiasouthern.edu)

# Table of Contents

1. Review: Graphs
  - Basic Graph Definitions (B.4)
  - Representations of Graphs (22.1)
2. Review: Graph Traversal
  - Breadth-First Search (BFS) (22.2)
  - Depth-First Search (DFS) (22.3)
  - Classification of Edges (22.3)
3. Topological Sort (22.4)
  - Application: Longest Path in a DAG
4. Strongly Connected Components (22.5)



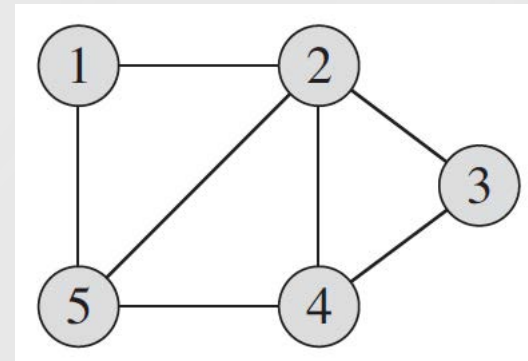
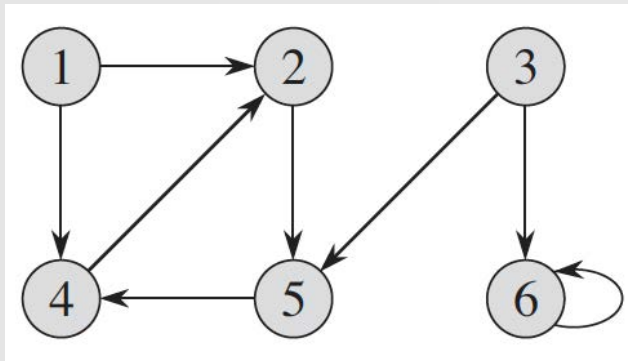
# Review: Graphs

## Basic Graph Definitions

# Directed and Undirected Graphs (1/2)

- A **graph**  $G = (V, E)$  consists of a **vertex set**  $V$  of  $n = |V|$  vertices/nodes and an **edge set**  $E$  of  $m = |E|$  edges.
  - **Directed graph (digraph)**: Edge  $(u, v)$  goes from vertex  $u$  to vertex  $v$ .
    - $(u, v)$  is an **outgoing edge** for  $u$  and an **incoming edge** for  $v$ .
    - $(v, v)$  is a **self-loop** goes from  $v$  to itself.
  - **Undirected graph**:  $(u, v)$  and  $(v, u)$  are the same edge, with  $u \neq v$ .

- **Examples:**



# Directed and Undirected Graphs (2/2)

- In an **undirected graph**, the **degree** of a vertex  $v$  is:

$\deg(v)$  = the number of edges that touch  $v$

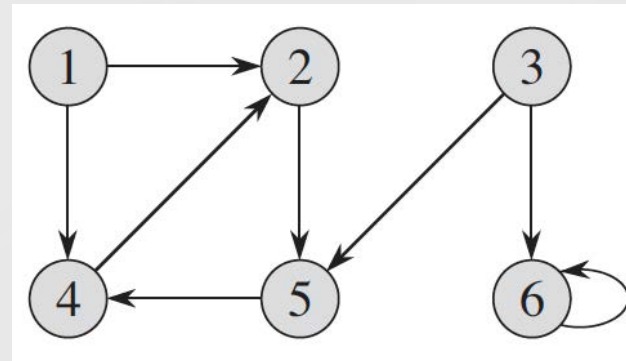
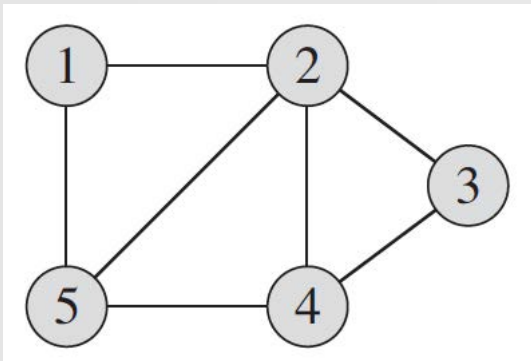
- In a **directed graph**, the **degree** of a vertex  $v$  is:

$$\deg(v) = \deg^-(v) + \deg^+(v),$$

where

- the **in-degree** of  $v$  is  $\deg^-(v)$  = the number of incoming edges for  $v$
- the **out-degree** of  $v$  is  $\deg^+(v)$  = the number of edges outgoing from  $v$

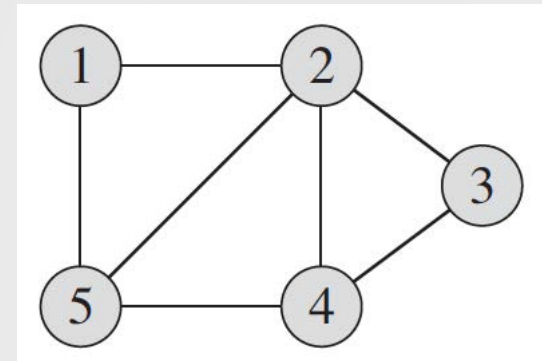
- **Examples:**



# Simple Path and Cycle

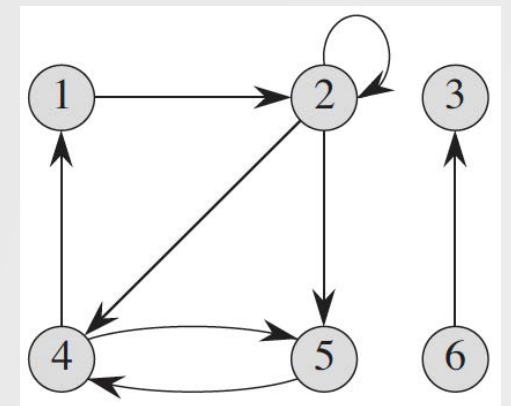
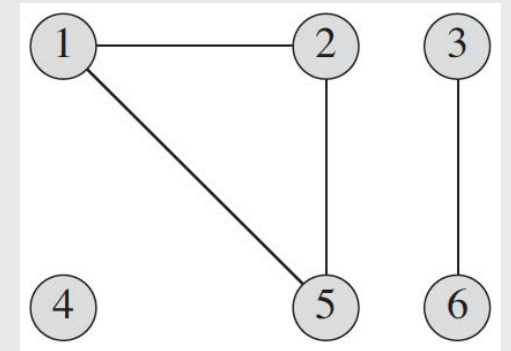
- A **path** is a sequence of vertices  $v_0, v_1, \dots, v_k$  such that there exists an edge  $(v_{i-1}, v_i)$  for  $i = 1, 2, \dots, k$ .
- A **simple path** is a path where all vertices in the path are distinct.
- A **cycle** is a path with  $v_0 = v_k$ .
- A **simple cycle** is a cycle where all vertices  $v_1, v_2, \dots, v_k$  are distinct.
- A graph with no cycles is called an **acyclic graph**.
- Unless specified otherwise, we **assume**
  - No multiple edges connecting two vertices
  - A path is a **simple path**
  - A cycle is a **simple cycle**

**Example:**



# Connectivity in Graphs

- An **undirected graph**  $G = (V, E)$  is called **connected** if for every pair of vertices  $u, v \in V$ , there exists a path from  $u$  to  $v$ .
  - A **tree** is a **connected acyclic** graph.
- A **connected component** of an **undirected graph**  $G$  is a maximal connected subgraph of  $G$ .
  - **Example**: the subgraph on vertex set  $\{1, 2, 5\}$
- A **directed graph**  $G = (V, E)$  is called **strongly-connected** if for every pair of vertices  $u, v \in V$ , there exist a path from  $u$  to  $v$  and a path from  $v$  to  $u$ .
- A **strongly connected component** of a **directed graph**  $G$  is a maximal strongly connected subgraph of  $G$ .
  - **Example**: the subgraph on vertex set  $\{1, 2, 4, 5\}$







# Review: Graphs

## Representations of Graphs



# Graph Representation

- Given graph  $G = (V, E)$ , either **directed** or **undirected**, we represent the vertex set  $V$  by  $G.V$  and edge set  $E$  by  $G.E$  in pseudocode.
- Two common ways to represent graphs for algorithms:
  - **Adjacency lists**
  - **Adjacency matrix**
- When expressing the **running time** of a graph algorithm, it's often in terms of both  $n = |V|$  and  $m = |E|$ .
- In asymptotic notation — and **only** in asymptotic notation — we may drop the cardinality.
  - **Example:**  $O(V + E) = O(n + m)$

# Graph Representation: Adjacency Matrix

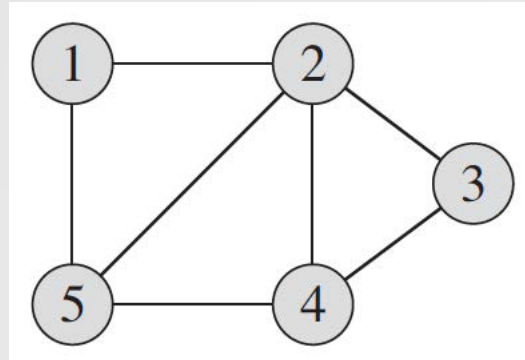
Represent  $G = (V, E)$ , with  $n = |V|$  and  $m = |E|$ , by

- A  $n \times n$  matrix  $A = \{a_{ij}\}$
- $a_{ij} = \begin{cases} 1, & \text{if } (i, j) \in E \\ 0, & \text{otherwise} \end{cases}$

**Advantage:** can check if some edge  $(u, v) \in E$  in  $\Theta(1)$  time.

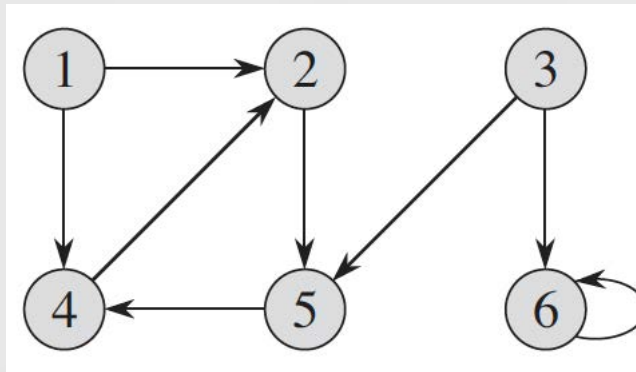
**Disadvantage:** requires  $\Theta(n^2)$  space even when  $m \ll n^2$ .

**Example 1:**



	1	2	3	4	5
1	0	1	0	0	1
2	1	0	1	1	1
3	0	1	0	1	0
4	0	1	1	0	1
5	1	1	0	1	0

**Example 2:**



	1	2	3	4	5	6
1	0	1	0	1	0	0
2	0	0	0	0	1	0
3	0	0	0	0	1	1
4	0	1	0	0	0	0
5	0	0	0	1	0	0
6	0	0	0	0	0	1

# Graph Representation: Adjacency Lists (1/2)

Represent  $G = (V, E)$ , with  $n = |V|$  and  $m = |E|$ , by

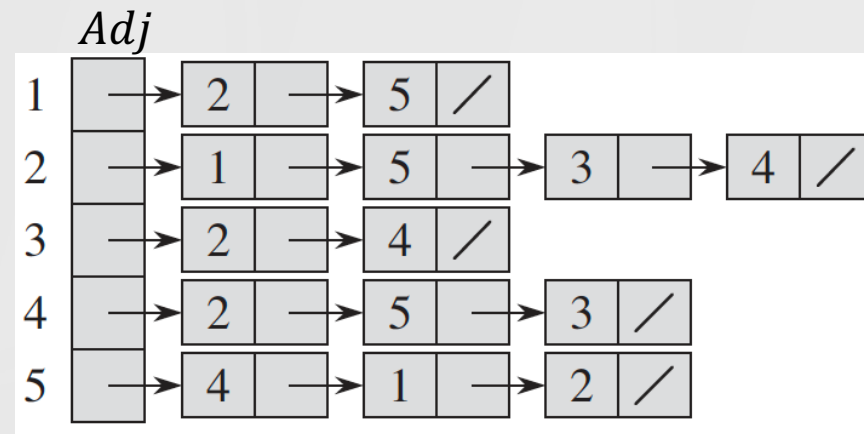
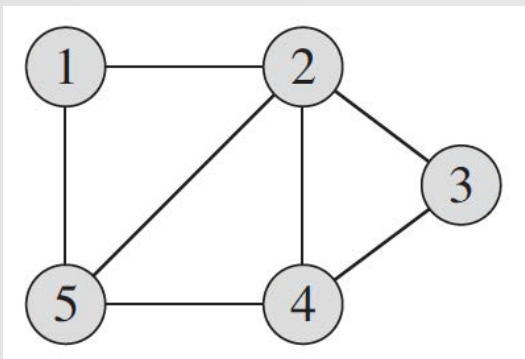
- An array *Adj* of  $n$  lists.
- List *Adj*[ $u$ ] has all vertices  $v$  such that  $(u, v) \in E$ .

**Disadvantage:** requires  $O(|Adj(u)|)$  time to check if  $(u, v) \in E$ .

In an **undirected graph**, total length of the  $n$  lists =  $\sum_{u \in V} |Adj(u)| = 2m$ .

**Advantage:**  $\Theta(n + m)$  space, better than  $\Theta(n^2)$  when  $m \ll n^2$ .

**Example 1:**



# Graph Representation: Adjacency Lists (2/2)

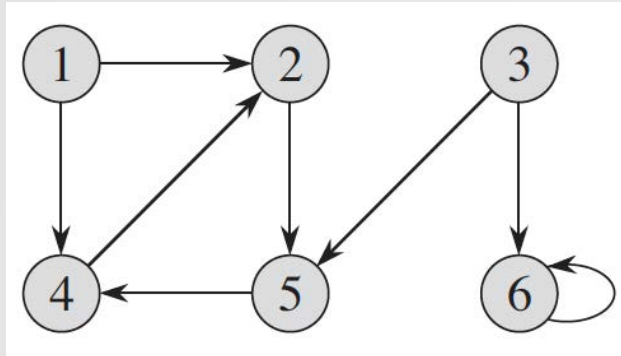
Represent  $G = (V, E)$ , with  $n = |V|$  and  $m = |E|$ , by

- An array *Adj* of  $n$  lists.
- List *Adj*[ $u$ ] has all vertices  $v$  such that  $(u, v) \in E$ .

In a **digraph**, total length of the  $n$  lists =  $\sum_{u \in V} |Adj(u)| = m$ .

**Space** is still  $\Theta(n + m)$ .

**Example 2:**



<i>Adj</i>			
1	→	2	→ 4 /
2	→	5	/
3	→	6	→ 5 /
4	→	2	/
5	→	4	/
6	→	6	/

**Note:** In this course, unless specified otherwise, we assume graphs are represented by *adjacency lists*.



# Review: Graph Traversal

## Breadth-First Search (BFS)

# Breadth-First Search (1/2)

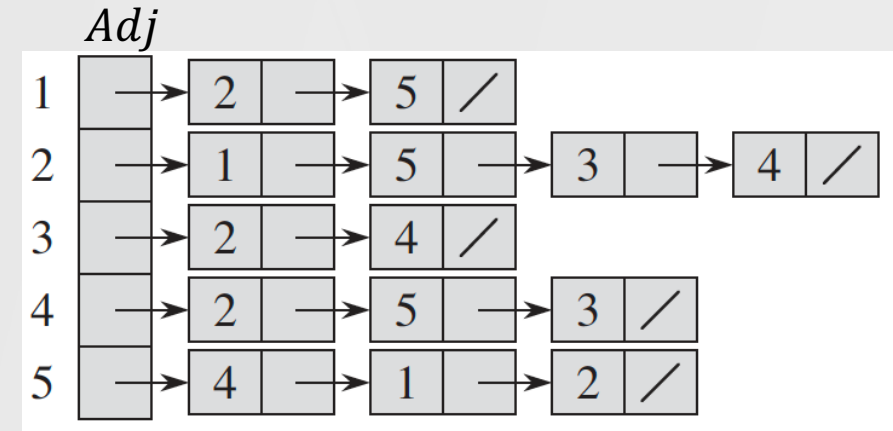
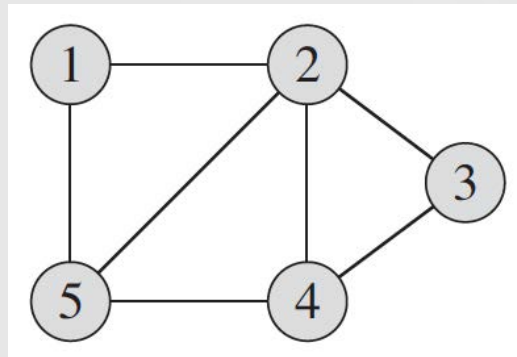
BFS( $G, s$ )

```

1  for each vertex  $u \in G.V - \{s\}$ 
2       $u.color = \text{WHITE}$ 
3       $u.d = \infty$ 
4       $u.\pi = \text{NIL}$ 
5   $s.color = \text{GRAY}$ 
6   $s.d = 0$ 
7   $s.\pi = \text{NIL}$ 
8   $Q = \emptyset$ 
9  ENQUEUE( $Q, s$ )
10 while  $Q \neq \emptyset$ 
11      $u = \text{DEQUEUE}(Q)$ 
12     for each  $v \in G.Adj[u]$ 
13         if  $v.color == \text{WHITE}$ 
14              $v.color = \text{GRAY}$ 
15              $v.d = u.d + 1$ 
16              $v.\pi = u$ 
17             ENQUEUE( $Q, v$ )
18      $u.color = \text{BLACK}$ 
    
```

Three attributes for each vertex:

- $v.color = \text{WHITE}$  (unvisited) or  $\text{GRAY}$  (discovered) or  $\text{BLACK}$  (finished)
- $v.d$  = distance (smallest #edges) from  $s$  to  $v$
- $v.\pi$  = the predecessor of  $v$  in the *breadth-first tree*
- **Example:**



$v$	1	2	3	4	5
$v.\pi$	NIL	1	2	2	1
$v.d$	0	1	2	2	1

# Breadth-First Search (2/2)

**BFS( $G, s$ )**

```
1  for each vertex  $u \in G.V - \{s\}$ 
2       $u.color = \text{WHITE}$ 
3       $u.d = \infty$ 
4       $u.\pi = \text{NIL}$ 
5   $s.color = \text{GRAY}$ 
6   $s.d = 0$ 
7   $s.\pi = \text{NIL}$ 
8   $Q = \emptyset$ 
9  ENQUEUE( $Q, s$ )
10 while  $Q \neq \emptyset$ 
11      $u = \text{DEQUEUE}(Q)$ 
12     for each  $v \in G.Adj[u]$ 
13         if  $v.color == \text{WHITE}$ 
14              $v.color = \text{GRAY}$ 
15              $v.d = u.d + 1$ 
16              $v.\pi = u$ 
17             ENQUEUE( $Q, v$ )
18      $u.color = \text{BLACK}$ 
```

**BFS( $G$ )**

```
for each vertex  $u \in G.V$ 
     $u.color = \text{WHITE}$ 
     $u.d = \infty$ 
     $u.\pi = \text{NIL}$ 
for each  $u \in G.V$ 
    if  $u.color == \text{WHITE}$ 
        BFS-VISIT( $G, u$ )
```

**BFS-VISIT( $G, s$ )**

// lines 5-18 of **BFS( $G, s$ )**

**Running time of **BFS( $G$ )**:**

- Using adjacency matrix:

$$\Theta\left(n + \sum_{v \in V} n = n + n^2\right) \\ = \Theta(n^2)$$

- Using adjacency lists:

$$\Theta\left(n + \sum_{v \in V} \deg(v) = n + 2m\right) \\ = \Theta(n + m)$$

**Warning:** By **BFS( $G, s$ )**, vertices in other connected components wouldn't be discovered!!!





# Review: Graph Traversal

## Depth-First Search (DFS)

# Depth-First Search (1/2)

DFS( $G$ )

```

1  for each vertex  $u \in G.V$ 
2       $u.color = \text{WHITE}$ 
3       $u.\pi = \text{NIL}$ 
4   $time = 0$ 
5  for each vertex  $u \in G.V$ 
6      if  $u.color == \text{WHITE}$ 
7          DFS-VISIT( $G, u$ )
    
```

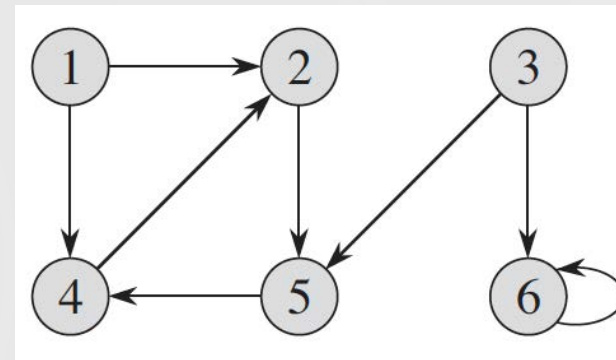
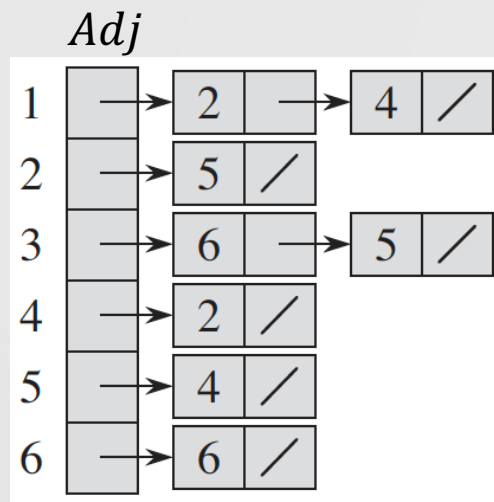
DFS-VISIT( $G, u$ )

```

1   $time = time + 1$ 
2   $u.d = time$ 
3   $u.color = \text{GRAY}$ 
4  for each  $v \in G.Adj[u]$ 
5      if  $v.color == \text{WHITE}$ 
6           $v.\pi = u$ 
7          DFS-VISIT( $G, v$ )
8   $u.color = \text{BLACK}$ 
9   $time = time + 1$ 
10  $u.f = time$ 
    
```

Three attributes for each vertex:

- $v.color = \text{WHITE}$  (unvisited) or  $\text{GRAY}$  (discovered) or  $\text{BLACK}$  (finished)
- $v.\pi$  = the predecessor of  $v$  in the *depth-first tree/forest*
- $v.d$  = discovery time of  $v$
- $v.f$  = finish time of  $v$
- **Example:**



$v$	1	2	3	4	5	6
$v.\pi$	NIL	1	NIL	5	2	3
$v.d$	1	2	9	4	3	10
$v.f$	8	7	12	5	6	11

# Depth-First Search (2/2)

DFS( $G$ )

```
1  for each vertex  $u \in G.V$ 
2       $u.color = \text{WHITE}$ 
3       $u.\pi = \text{NIL}$ 
4   $time = 0$ 
5  for each vertex  $u \in G.V$ 
6      if  $u.color == \text{WHITE}$ 
7          DFS-VISIT( $G, u$ )
```

DFS-VISIT( $G, u$ )

```
1   $time = time + 1$ 
2   $u.d = time$ 
3   $u.color = \text{GRAY}$ 
4  for each  $v \in G.Adj[u]$ 
5      if  $v.color == \text{WHITE}$ 
6           $v.\pi = u$ 
7          DFS-VISIT( $G, v$ )
8   $u.color = \text{BLACK}$ 
9   $time = time + 1$ 
10  $u.f = time$ 
```

- **Running time of DFS( $G$ ):**

- Using adjacency matrix:

$$\Theta\left(n + \sum_{v \in V} n = n + n^2\right) = \Theta(n^2)$$

- Using adjacency lists:

$$\Theta\left(n + \sum_{v \in V} \deg(v) = n + 2m\right) = \Theta(n + m)$$



# Review: Graph Traversal

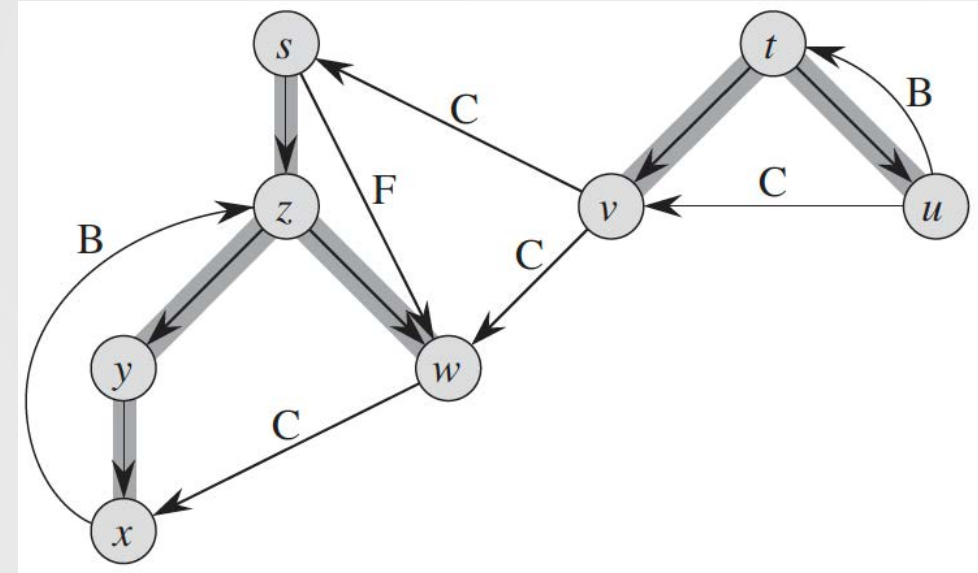
## Classification of Edges

# Classification of Edges

Based on the **breadth-first tree/forest** or **depth-first tree/forest**, edges in the original graph can be classified into the following four types.

1. **Tree edge**: an edge  $(u, v)$  in the **breadth-first** or **depth-first tree/forest**
2. **Back edge**: a non-tree edge  $(u, v)$  where  $v$  is an **ancestor** of  $u$  in the **tree**, including **self-loops** in digraphs
3. **Forward edge**: a non-tree edge  $(u, v)$  where  $v$  is a **descendent** of  $u$  in the **tree**  
“back” = “forward” in **undirected** graphs.
4. **Cross edge**: any other edge

**Example:** DFS for a digraph



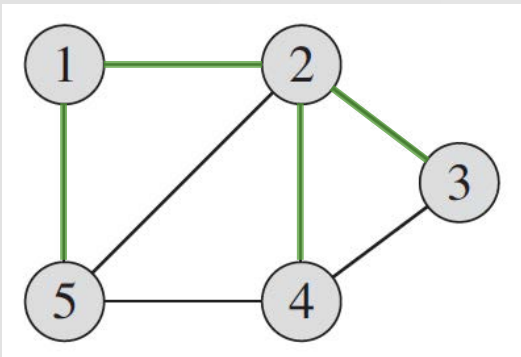
- Bold gray: Tree edge
- B: Back edge
- F: Forward edge
- C: Cross edge

# BFS Edges

BFS for **undirected** graphs:

- Have only **tree** and **cross edges**
- No **back/forward edges**

**Example:**



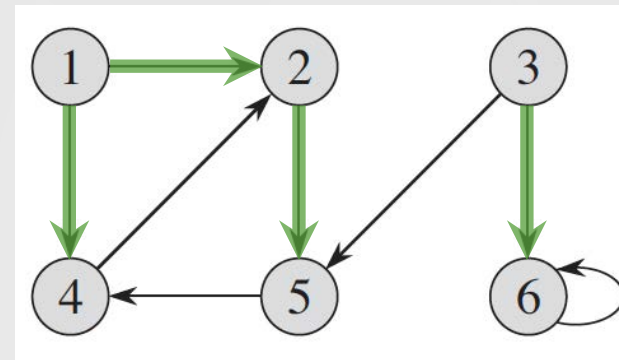
Tree edges: (1, 2), (1, 5), (2, 3), (2, 4)

Cross edges: (2, 5), (3, 4), (4, 5)

BFS for **directed** graphs:

- Have only **tree**, **back**, and **cross edges**
- No **forward edges**

**Example:**



Tree edges: (1, 2), (1, 4), (2, 5), (3, 6)

Back edge: (6, 6)

Cross edge: (3, 5), (4, 2), (5, 4)

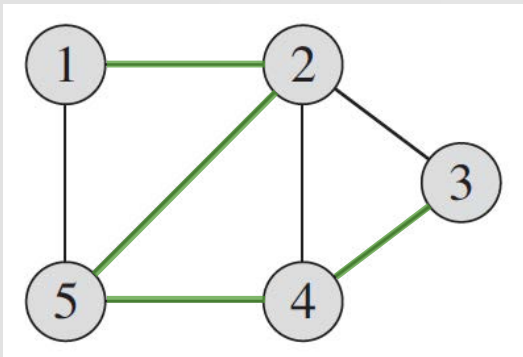


# DFS Edges

DFS for **undirected** graphs:

- Have only **tree** and **back/forward edges**
- No **cross edges**

**Example:**



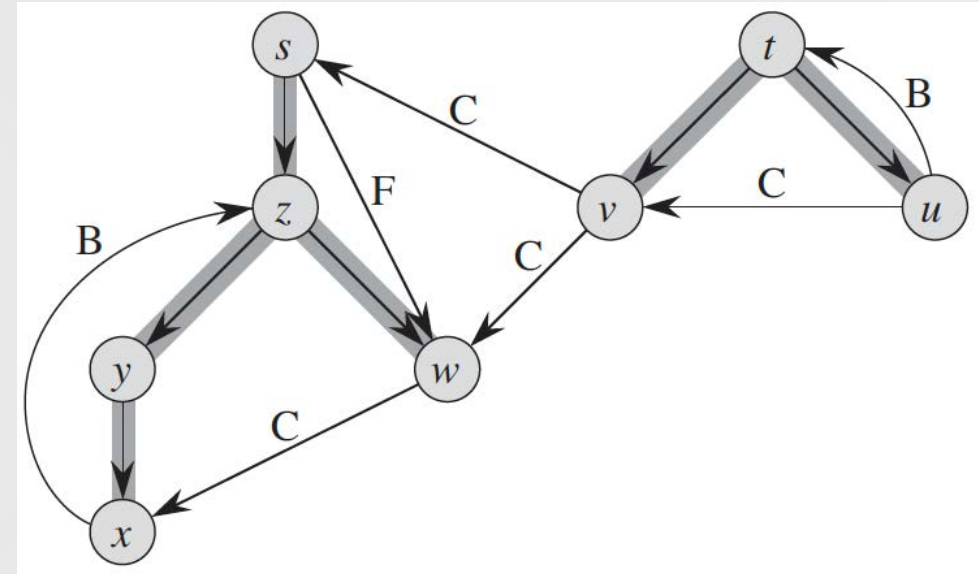
Tree edges: (1, 2), (2, 5), (3, 4), (4, 5)

Back/Forward edges: (1, 5), (2, 3), (2, 4)

DFS for **directed** graphs:

- Can have all four types of **edges**

**Example:**



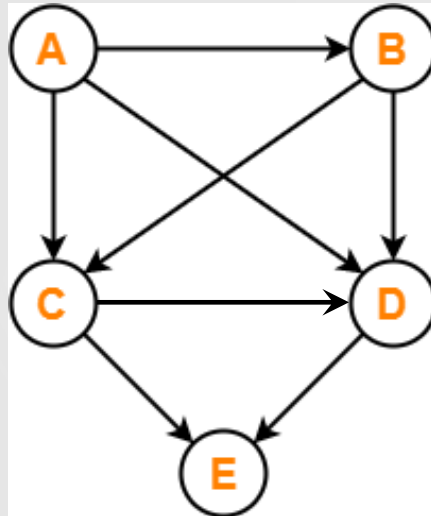




# Topological Sort

# Topological Sort

- **Topological Sort** (of a graph): A linear ordering of vertices such that if edge  $(u, v) \in E$ , then  $u$  appears somewhere before  $v$ .
- If a **directed** graph has a **topological sort**, we can find an assignment of a unique number  $\{1, 2, \dots, n\}$  to each vertex such that all edges are heading forward.
- **Example:**



Topological sort:

- A B C D E

# Topological Sort of A DAG

- **Directed Acyclic Graph (DAG):** A directed graph with no cycles.

**Theorem:**  $G$  is a DAG iff  $G$  has a topological sort.

## Proof.

- “ $\Leftarrow$ ”:
  - If  $G$  has a topological sort, we can find an assignment of a unique number  $\{1, 2, \dots, n\}$  to each vertex in  $G$  such that all edges are heading forward.
  - So, there must be no cycle in  $G \Rightarrow G$  is a DAG.
- “ $\Rightarrow$ ”:<sup>\*</sup>
  - Algorithm TOPOLOGICAL-SORT will find a topological sort of a DAG.

---

*\* For “ $\Rightarrow$ ”, see the complete proof of Theorem 22.12 on p.614 of the textbook.*

# Find Topological Sort

## TOPOLOGICAL-SORT( $G$ )

1. Call DFS( $G$ ) to compute finishing times  $v.f$  for each vertex  $v \in G.V$ 
  - During DFS, as each vertex is finished, insert it onto the front of a linked list.
2. **return** the linked list of vertices

### DFS( $G$ )

```
1  for each vertex  $u \in G.V$ 
2       $u.color = \text{WHITE}$ 
3       $u.\pi = \text{NIL}$ 
4   $time = 0$ 
5  for each vertex  $u \in G.V$ 
6      if  $u.color == \text{WHITE}$ 
7          DFS-VISIT( $G, u$ )
```

### DFS-VISIT( $G, u$ )

```
1   $time = time + 1$ 
2   $u.d = time$ 
3   $u.color = \text{GRAY}$ 
4  for each  $v \in G.Adj[u]$ 
5      if  $v.color == \text{WHITE}$ 
6           $v.\pi = u$ 
7          DFS-VISIT( $G, v$ )
8   $u.color = \text{BLACK}$ 
9   $time = time + 1$ 
10  $u.f = time$ 
```

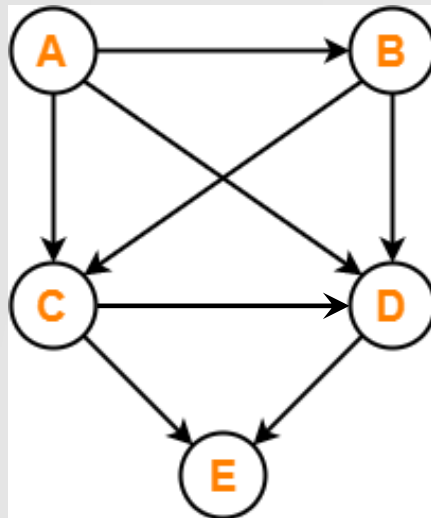
- There is no need to perform a sorting algorithm for decreasing finishing times.
- It can be done as part of DFS.
- **Running time:**  $\Theta(n + m)$  (same as DFS)

# Topological Sort Example

## TOPOLOGICAL-SORT( $G$ )

1. Call DFS( $G$ ) to compute finishing times  $v.f$  for each vertex  $v \in G.V$ 
  - During DFS, as each vertex is finished, insert it onto the front of a linked list.
2. **return** the linked list of vertices

### Example:



# Correctness of Topological Sort

**Theorem.** Algorithm TOPOLOGICAL-SORT produces a topological sort of the input DAG  $G$ .<sup>\*</sup>

**Proof.** Show that for every edge  $(u, v) \in E$ ,  $u.f > v.f$ .

**Case 1:**  $u.d < v.d$

- Based on DFS,  $v$  becomes BLACK before  $u$ .
- Then, we have  $u.f > v.f$

**Case 2:**  $u.d > v.d$

- $G$  has no cycle, so there is no path from  $v$  to  $u$ .
- $u$  will not be visited by DFS-VISIT( $G, v$ ).
- $u.d > v.d$  implies  $u.f > v.f$

DFS( $G$ )

```
1  for each vertex  $u \in G.V$ 
2       $u.color = WHITE$ 
3       $u.\pi = NIL$ 
4   $time = 0$ 
5  for each vertex  $u \in G.V$ 
6      if  $u.color == WHITE$ 
7          DFS-VISIT( $G, u$ )
```

DFS-VISIT( $G, u$ )

```
1   $time = time + 1$ 
2   $u.d = time$ 
3   $u.color = GRAY$ 
4  for each  $v \in G.Adj[u]$ 
5      if  $v.color == WHITE$ 
6           $v.\pi = u$ 
7          DFS-VISIT( $G, v$ )
8   $u.color = BLACK$ 
9   $time = time + 1$ 
10  $u.f = time$ 
```

---

<sup>\*</sup> See Theorem 22.12 on p.614 of the textbook.



# Topological Sort

## Longest Path in a DAG



# Longest Path in a DAG

- Given a DAG  $G$ , define  $L(G, v)$  as the length of the longest path in  $G$  starting with  $v$ .
- Then the length of the **longest path** in  $G$  will be

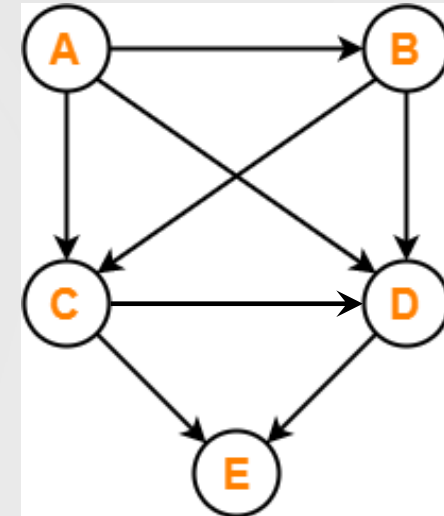
$$\max_{v \in V} \{L(G, v)\}$$

- If  $S$  is a **topological sort** of  $G$  and  $u$  is the first vertex in  $S$ , then

$$L(G, u) = \max_{v \in N^+(u)} \{L(G, v)\} + 1,$$

where  $N^+(u)$  is the set of out-neighbors of  $u$ .

**Example:**



# DP for Longest Path in DAG (1/3)

**Step 1:** Find a recurrence relation

- The length of the longest path in  $G$  starting with  $u$  is

$$L(G, u) = \begin{cases} 0, & \text{if } N^+(u) = \emptyset \\ 1 + \max_{v \in N^+(u)} \{L(G, v)\}, & \text{otherwise} \end{cases}$$

**Step 2:** Count #distinct recursive calls —  $n = |V|$

**Step 3:** Define an array  $L$  of size  $n$ .

- $L[k]$  will hold the value of  $L(G, v_k)$ , where  $v_k$  is the  $k$ -th vertex in the **topological sort** of  $G$ .
- Fill the array  $L$  according to the recurrence relation.
- The largest element in  $L$  will be the length of the longest path in  $G$ .

# DP for Longest Path in DAG (2/3)

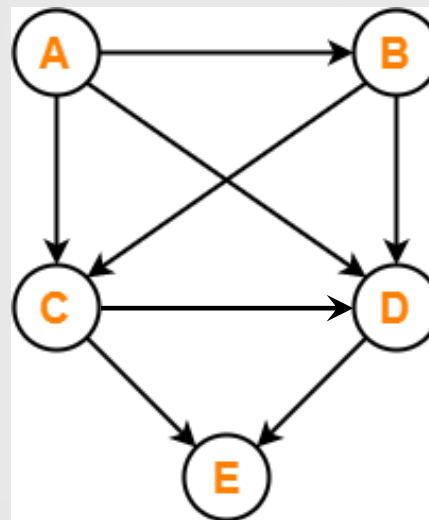
**Step 3 (cont'd):** Fill the array  $L$  according to the following recurrence

$$L[u] = \begin{cases} 0, & \text{if } N^+(u) = \emptyset \\ 1 + \max_{v \in N^+(u)} L[v], & \text{otherwise} \end{cases}$$

LONGEST-PATH-DAG( $G$ )

```
1  $S = \text{TOPOLOGICAL-SORT}(G)$ 
2 for each  $v$  in downward order of  $S$ 
3    $L[v] = 0$ 
4   for each  $u \in N^+[v]$ 
5     if  $1 + L[u] > L[v]$ 
6        $L[v] = 1 + L[u]$ 
```

**Example:**



$v$	A	B	C	D	E
$L[v]$					

**Running time:**  $\Theta(n + m)$

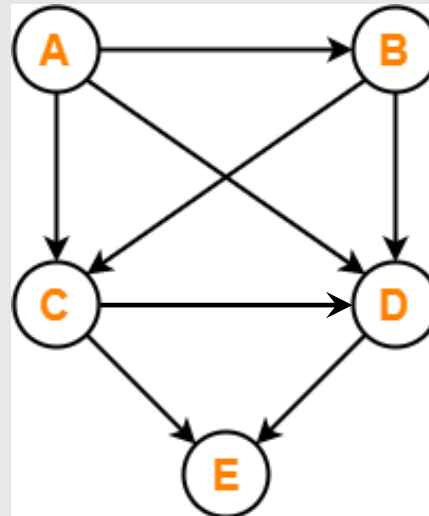
# DP for Longest Path in DAG (3/3)

**Step 4:** Extract a longest path from array  $L$ .

PRINT-LONGEST-PATH-DAG( $G, S, L$ )

```
1  $i = \text{FIND-MAX}(L)$  // return the index
2  $v = S[i]$ 
3 while  $v \neq \text{NIL}$ 
4   PRINT( $v$ )
5    $\text{nextnode} = \text{NIL}$ 
6   for each  $u \in N^+[v]$ 
7     if  $L[v] == 1 + L[u]$ 
8        $\text{nextnode} = u$ 
9    $v = \text{nextnode}$ 
```

**Example:**



$v$	A	B	C	D	E
$L[v]$	4	3	2	1	0

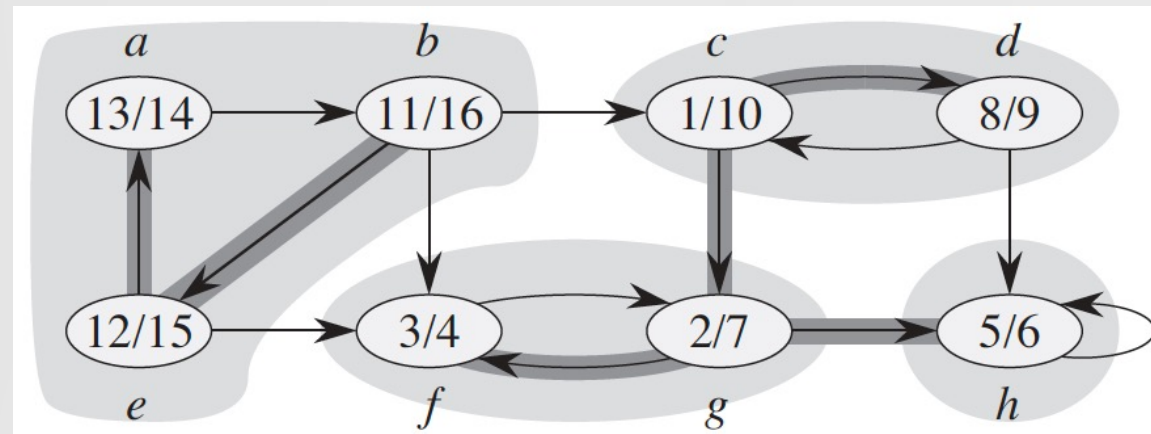
**Running time:**  $\Theta(n + m)$

An abstract network diagram with various nodes (dots) and edges (lines) connecting them. Some nodes are larger than others, and the connections form a complex web. The background is light gray with some faint geometric shapes like triangles.

# Strongly Connected Components

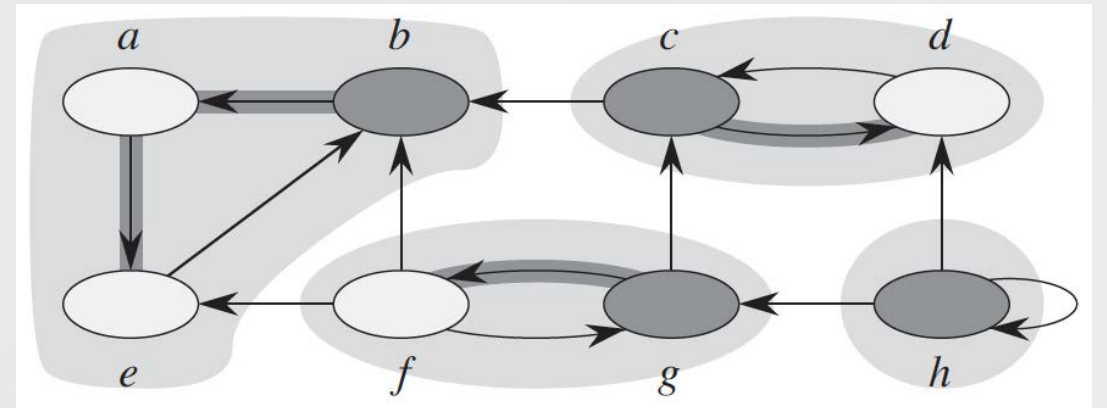
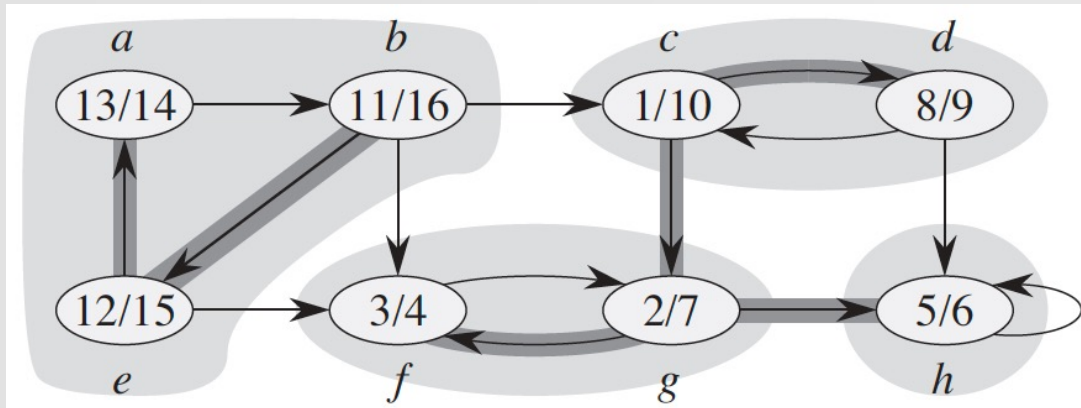
# Strongly Connected Components

- Given a **digraph**  $G = (V, E)$ , a **strongly connected component (SCC)** of  $G$  is a **maximal** set of vertices  $C \subseteq V$  such that for any two vertices  $u, v \in C$ , there is a path from  $u$  to  $v$  and also a path from  $v$  to  $u$ .
- Define  $SCC(u)$  as the set of all nodes that are **reachable** from  $u$  and that  $u$  is also **reachable** from every one of them.
- Claim 1:** If  $u$  and  $v$  are reachable from each other, then  $SCC(u) = SCC(v)$ .
- Example:**



# Properties of SCCs (1/3)

- Define  $G^T = (V, E^T)$  as the **transpose** of  $G$ , with all edges reversed.
- **Claim 2:**  $G$  and  $G^T$  have the same **SCCs**.
- **Claim 3:** The **SCCs** of  $G$  form a **partition** of  $V$  into  $\{C_1, C_2, \dots, C_k\}$ . That is,  $C_1 \cup C_2 \cup \dots \cup C_k = V$  and  $C_i \cap C_j = \emptyset$  for any  $i \neq j$ .
- **Example:**

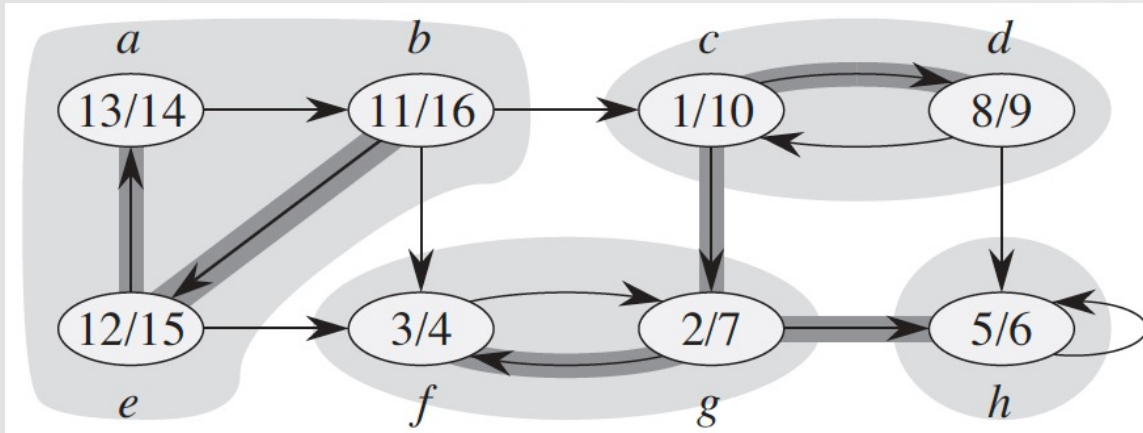




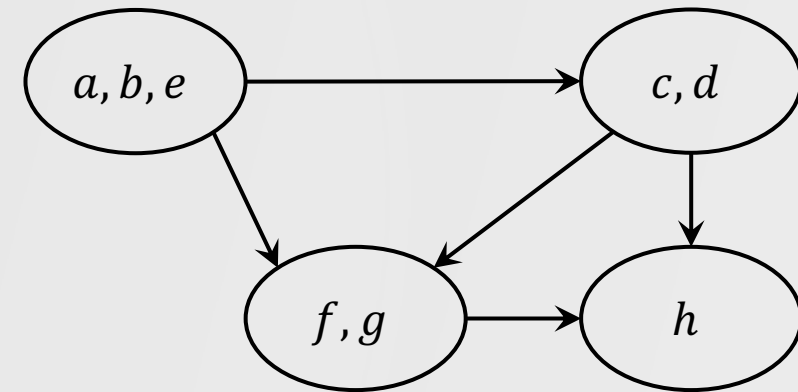
## Properties of SCCs (2/3)

- Create a **component graph**  $G_{SCC} = (V_{SCC}, E_{SCC})$ , where
  - $V_{SCC} = \{x_1, x_2, \dots, x_k\}$ , with each vertex  $x_i$  representing a **SCC**  $C_i$
  - $E_{SCC}$  has an edge  $(x_i, x_j)$  iff  $(u, v) \in E$  with  $u \in C_i$  and  $v \in C_j$ .

- **Example:**



$G$



$G_{SCC}$

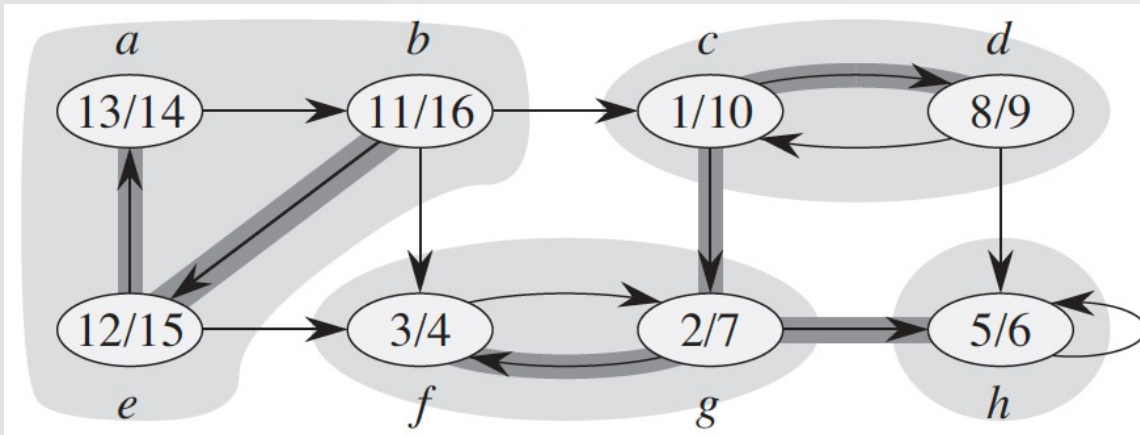
# Properties of SCCs (3/3)

**Claim 4:**  $G_{SCC}$  is a DAG.

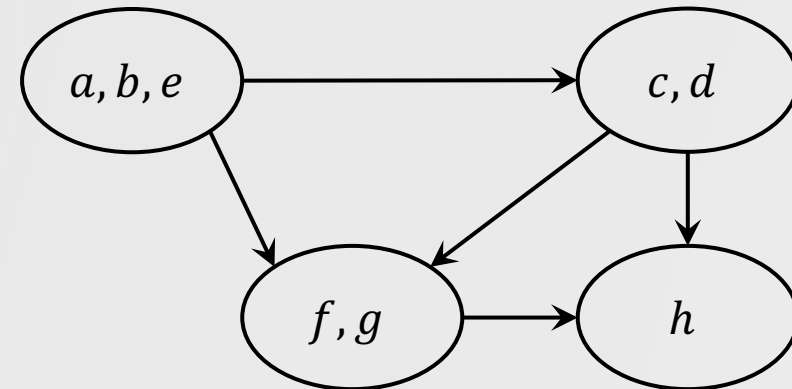
**Proof.** By contradiction.

- If  $G_{SCC}$  is not a DAG, then there is a cycle  $\langle x_i, x_j, \dots, x_i \rangle$  in  $G_{SCC}$ .
- Consider vertices  $v_i \in C_i$  and  $v_j \in C_j$ . There is a path from  $v_i$  to  $v_j$  and also a path from  $v_j$  to  $v_i$ .  $v_i$  and  $v_j$  should be in the same SCC. (**Claim 1**)

A contradiction:  $C_i$  and  $C_j$  are different SCCs.



$G$



$G_{SCC}$

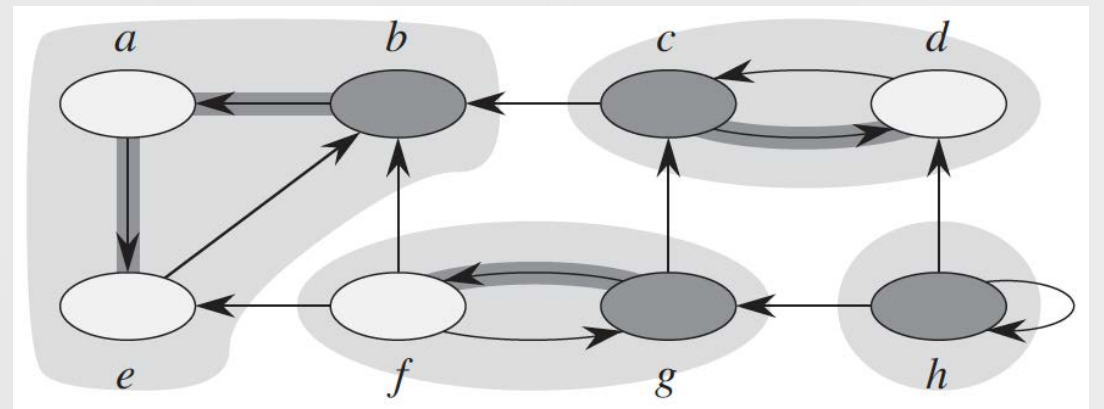
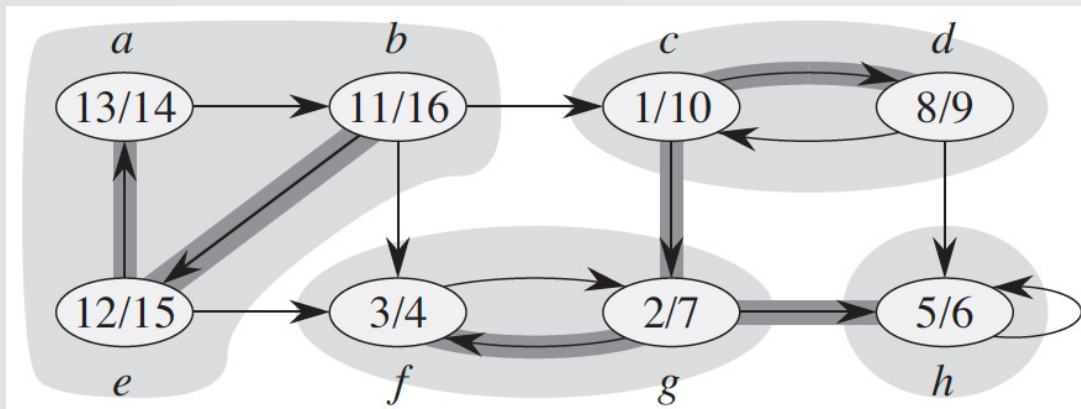
# Finding SCCs

$\text{SCC}(G)$

1. Call  $\text{DFS}(G)$  to get a decreasing  $v.f$  order
2. Create  $G^T$
3. Call  $\text{DFS}(G^T)$  with the main DFS loop traversing nodes in a decreasing  $v.f$  order (computed in step 1)
4. **return** the vertex set of each tree of the **depth-first forest** of  $G^T$  formed in step 3

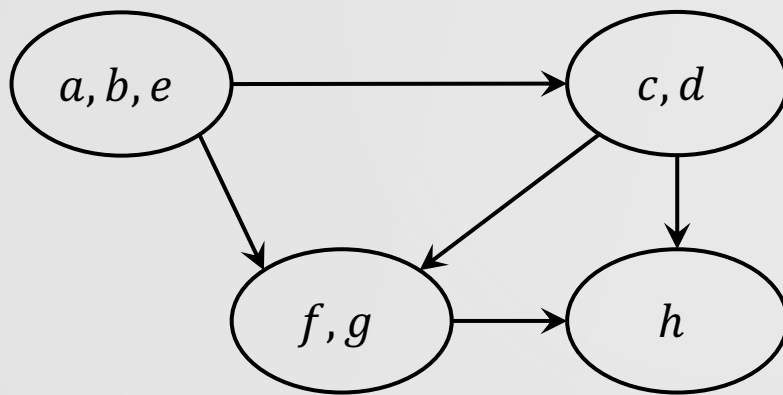
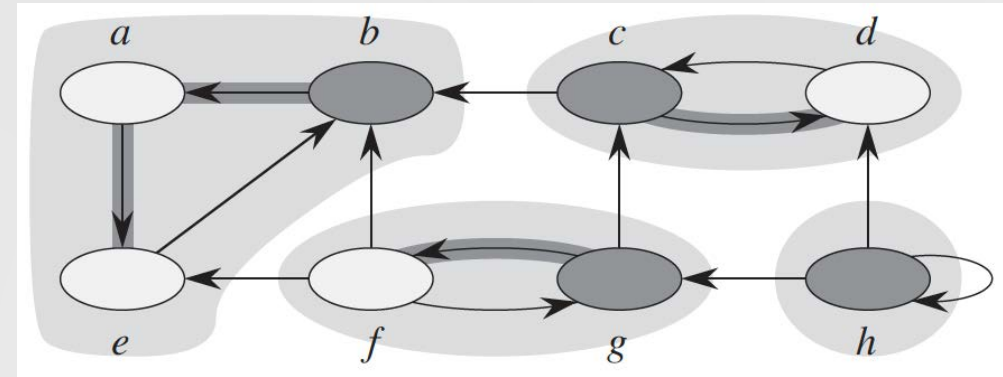
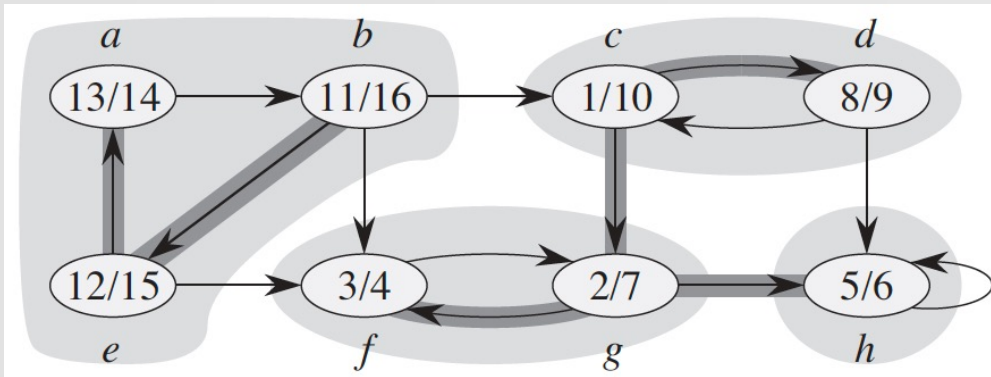
**Running time:**  $\Theta(n + m)$

**Example:**

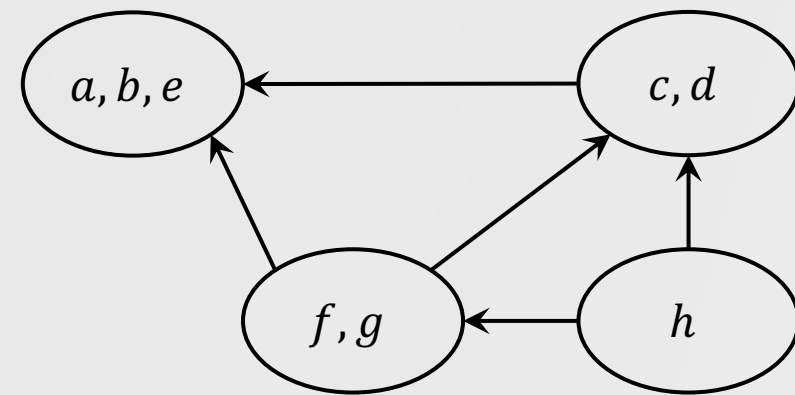


# Intuition for the Correctness *(Optional)* <sup>(1/5)</sup>

- First, observe that  $(G^T)_{SCC} = (G_{SCC})^T$ .
- Example:**



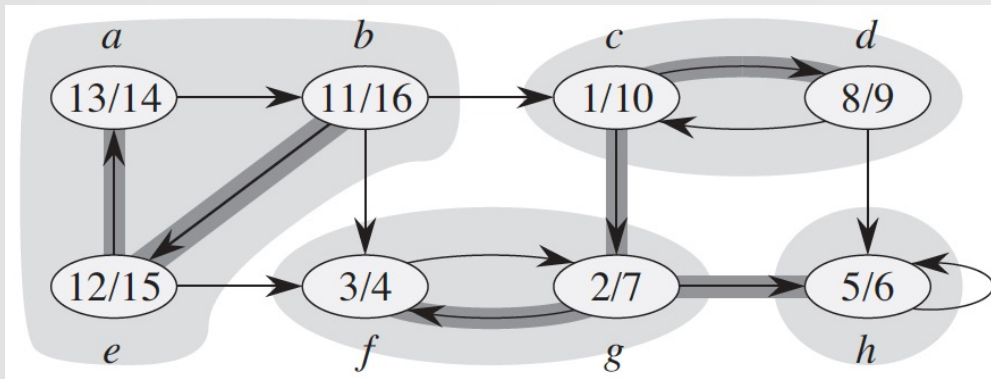
$G_{SCC}$



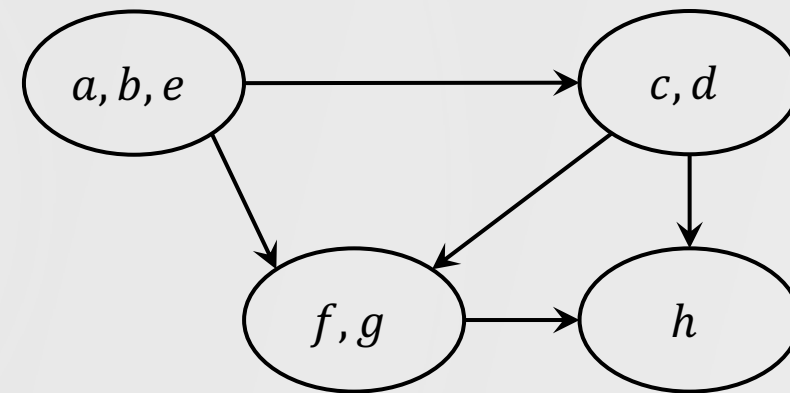
$(G^T)_{SCC}$

## Intuition for the Correctness (*Optional*) <sup>(2/5)</sup>

- For any SCC  $C_i$  of  $G$ , let  $w_i$  be the node with the largest finishing time.
- Let  $w_1, w_2, \dots, w_k$  be in descending order of finishing time.
- As  $G_{SCC}$  is a **DAG** (**Claim 4**),  $x_1, x_2, \dots, x_k$  is a **topological sort** of  $G_{SCC}$ .
- **Example:**



$G$

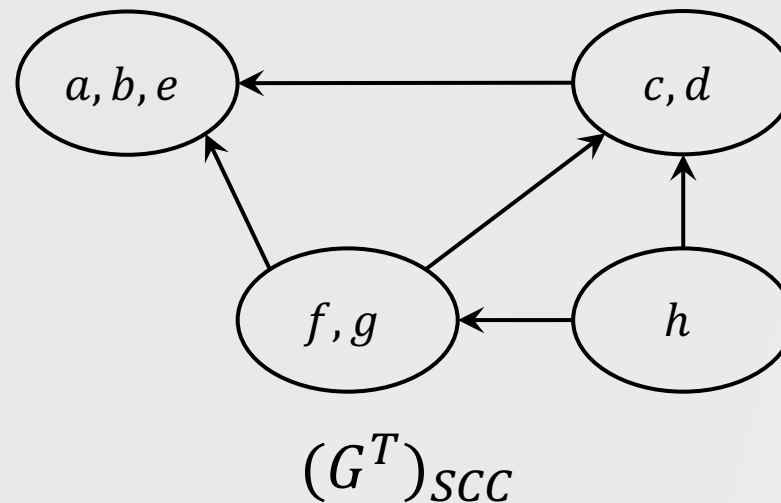
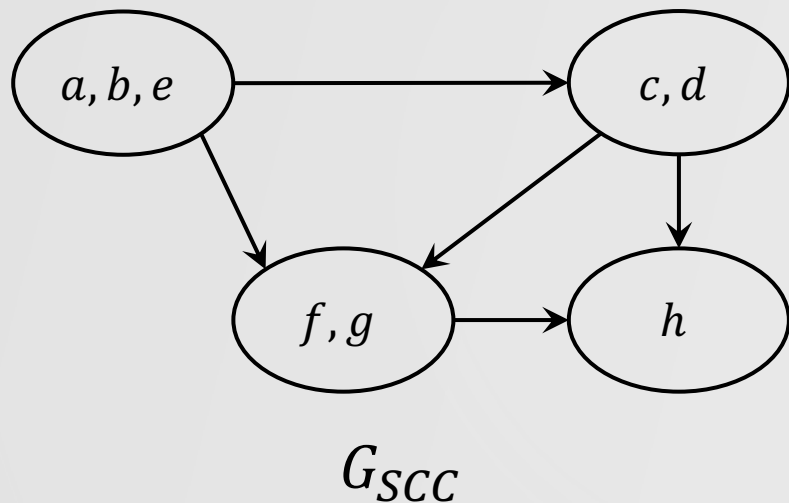


$G_{SCC}$

## Intuition for the Correctness *(Optional)* <sup>(3/5)</sup>

- As  $G_{SCC}$  is a **DAG** (Claim 4),  $x_1, x_2, \dots, x_k$  is a **topological sort** of  $G_{SCC}$ .
- So,  $x_1, x_2, \dots, x_k$  is the **inverse** of a **topological sort** of  $(G^T)_{SCC}$ .
- This means that not a single edge leaves  $x_1$  in  $(G^T)_{SCC}$ .

- **Example:**



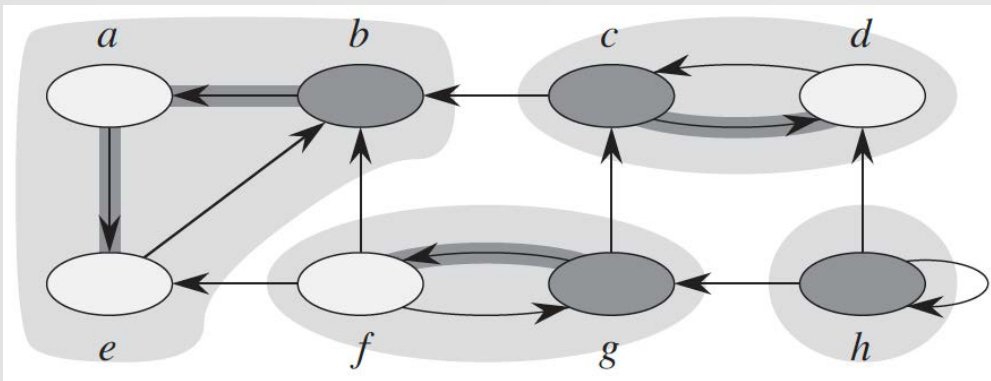


# Intuition for the Correctness (*Optional*) (4/5)

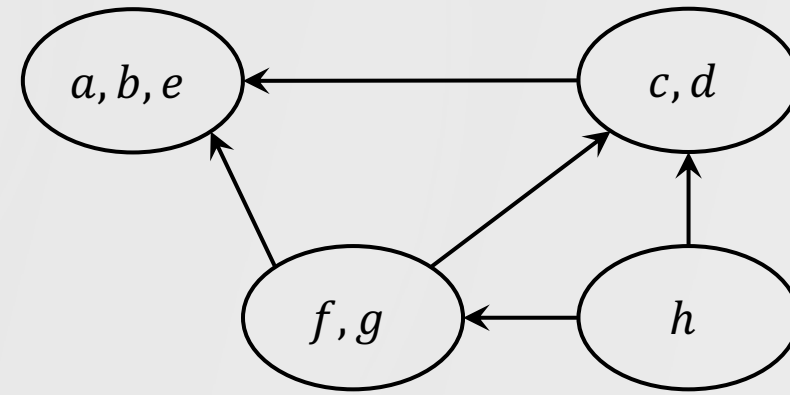
$\text{SCC}(G)$

1. Call  $\text{DFS}(G)$  to get a decreasing  $v.f$  order
2. Create  $G^T$
3. Call  $\text{DFS}(G^T)$  with the main DFS loop traversing nodes in a decreasing  $v.f$  order (computed in step 1)
4. **return** the vertex set of each tree of the **depth-first forest** of  $G^T$  formed in step 3

- Not a single edge leaves  $x_1$  in  $(G^T)_{\text{SCC}}$ .
- $w_1$  (with largest finishing time) is the first vertex in the  $\text{DFS}(G^T)$  call.
- Therefore, all vertices reachable from  $w_1$  are the vertices in  $\text{SCC}(w_1) = C_1$ .



$G^T$



$(G^T)_{\text{SCC}}$

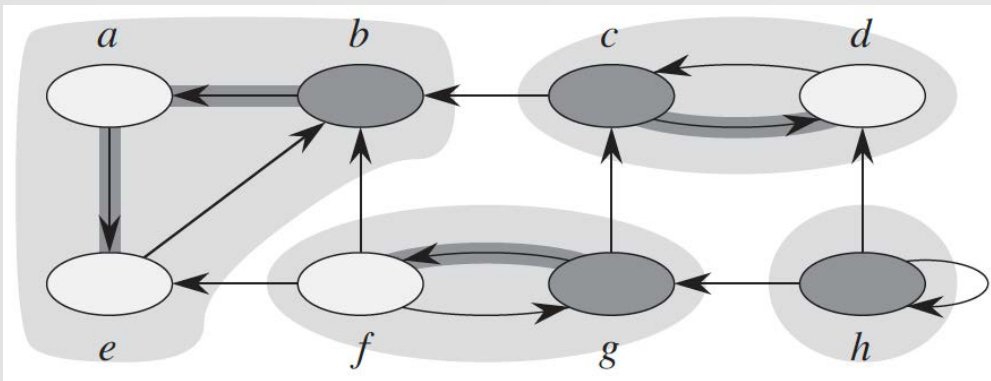


# Intuition for the Correctness (*Optional*) (5/5)

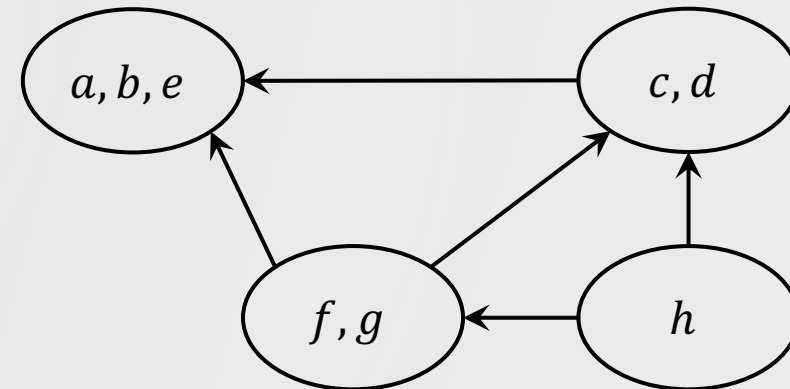
$\text{SCC}(G)$

1. Call  $\text{DFS}(G)$  to get a decreasing  $v.f$  order
2. Create  $G^T$
3. Call  $\text{DFS}(G^T)$  with the main DFS loop traversing nodes in a decreasing  $v.f$  order (computed in step 1)
4. **return** the vertex set of each tree of the **depth-first forest** of  $G^T$  formed in step 3

- Continue **inductively** to argue that:
- By the time  $w_i$  is discovered in the  $\text{DFS}(G^T)$  call, all the vertices in SCCs  $C_1, C_2, \dots, C_{i-1}$  are already BLACK, so  $w_i$  will only reach vertices in  $C_i$ .



$G^T$



$(G^T)_{\text{SCC}}$

**Thank you!**  
**Questions?**